

The background of the slide features a night-time photograph of a city skyline with numerous lights, viewed from a distance. In the foreground, several high-voltage electrical transmission towers and power lines are silhouetted against the dark sky. A semi-transparent dark blue rectangular box is overlaid on the right side of the image, containing the title and presenter information. To the right of this box, a faint, glowing blue network diagram with interconnected nodes and lines is visible.

Development and Testing of Resilience Grid Automation using RT simulations

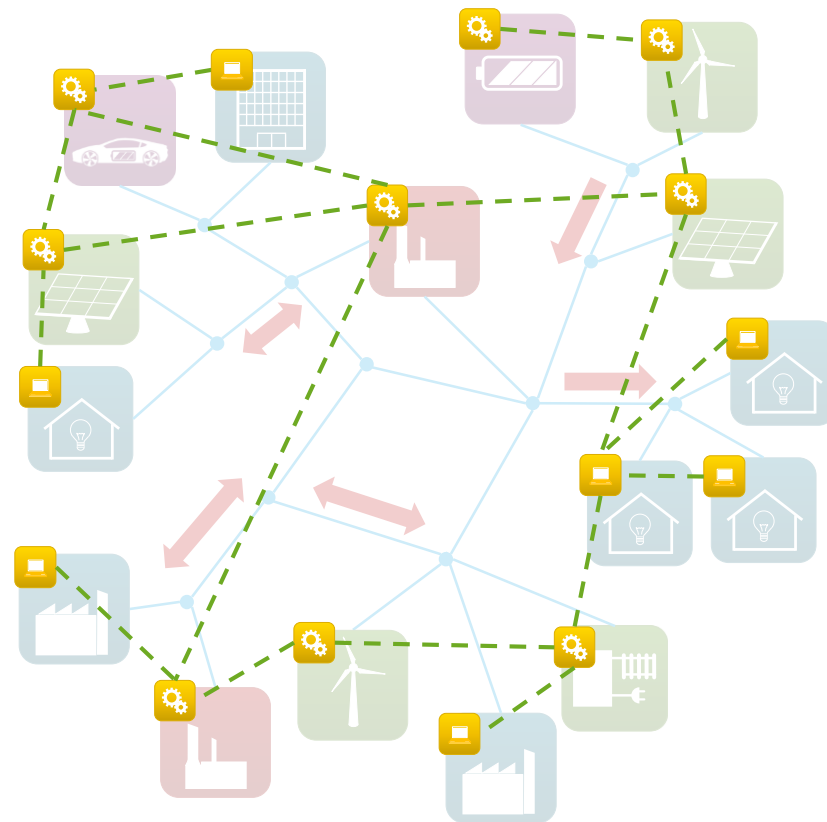
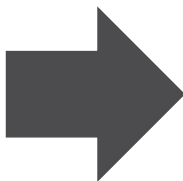
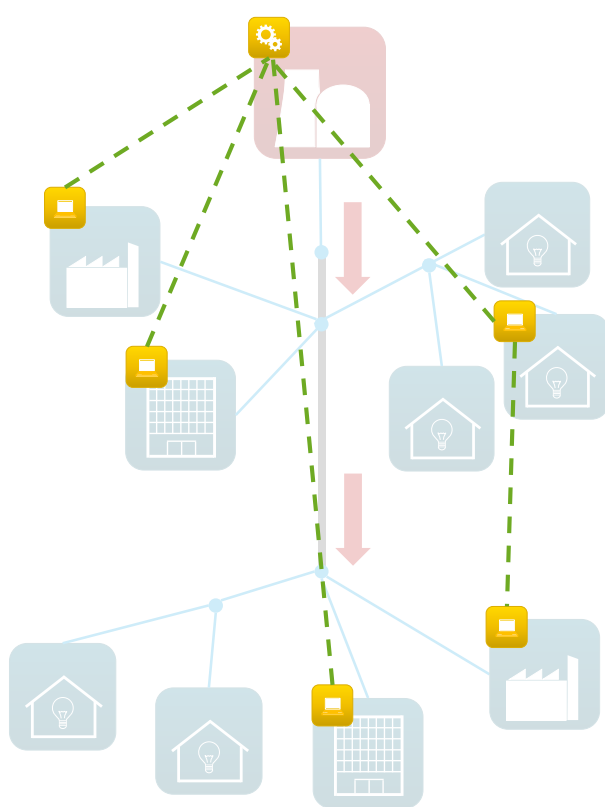
Carsten Krüger

29.10.2019



Motivation

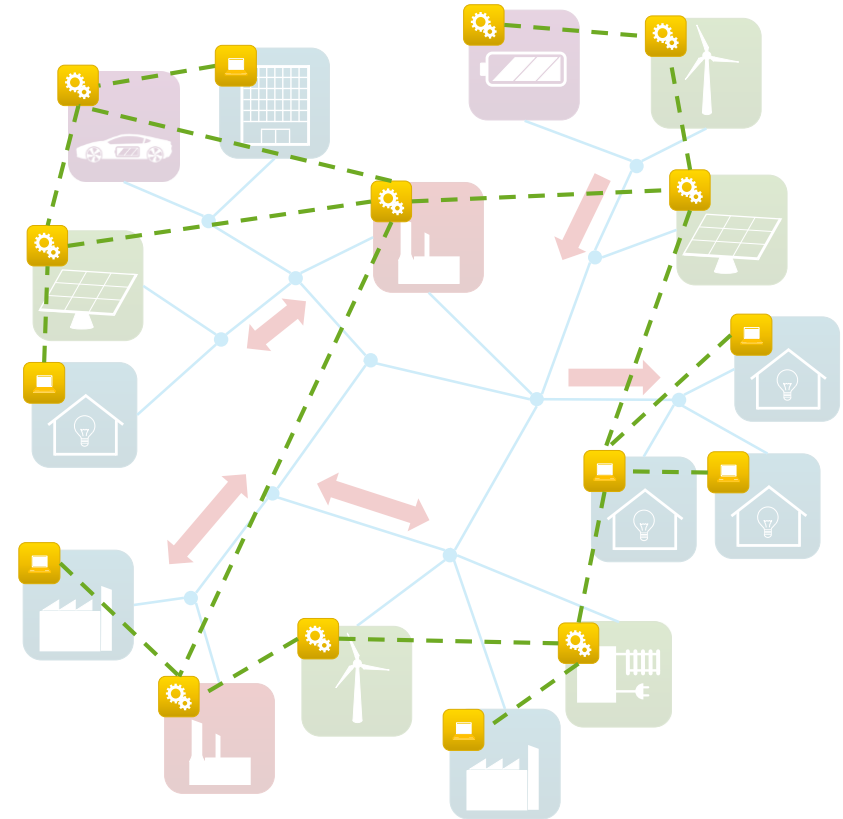
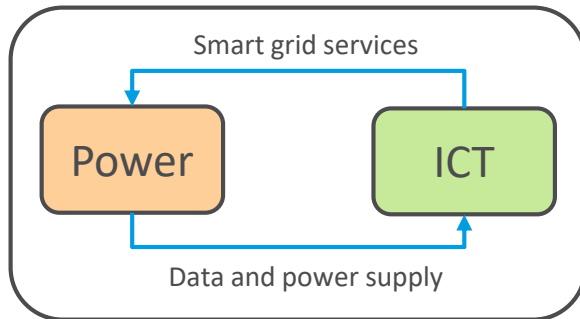
Paradigm Shift to Distributed Smart Grids



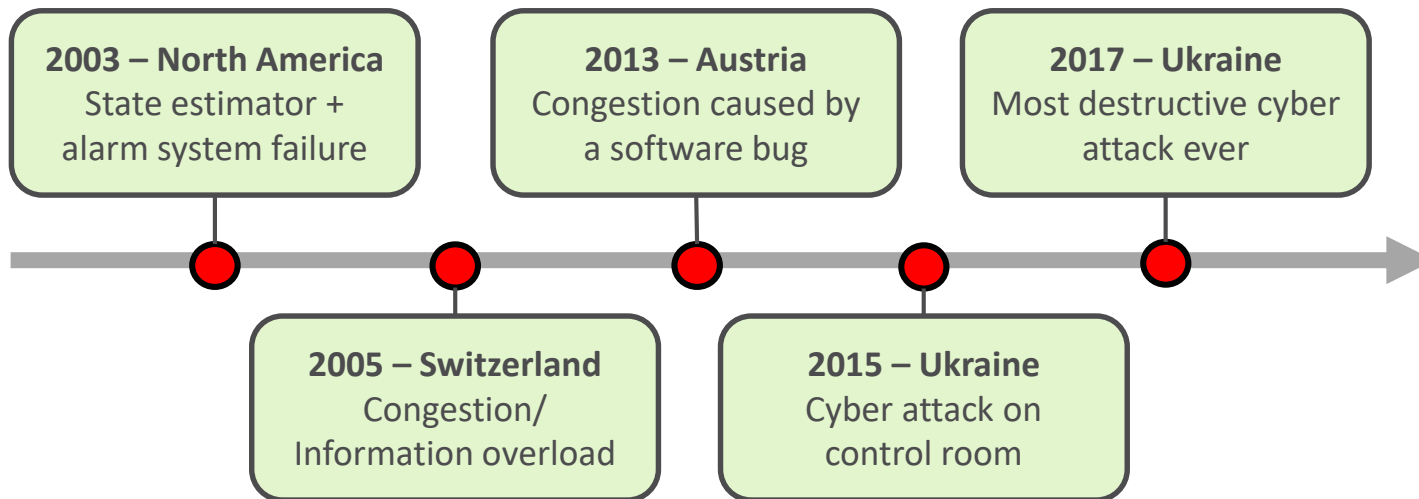
Motivation

Paradigm shift to Complex Smart Grids

- **DER** – Clean resource and too some extend flexible, but more uncertainties.
- **ICT (i.e. automation sys.)** enables better monitoring, operation, decision making and control
 - Smart grid services – State estimation, voltage control, unit commitment, etc.
 - Strong coupling between the systems



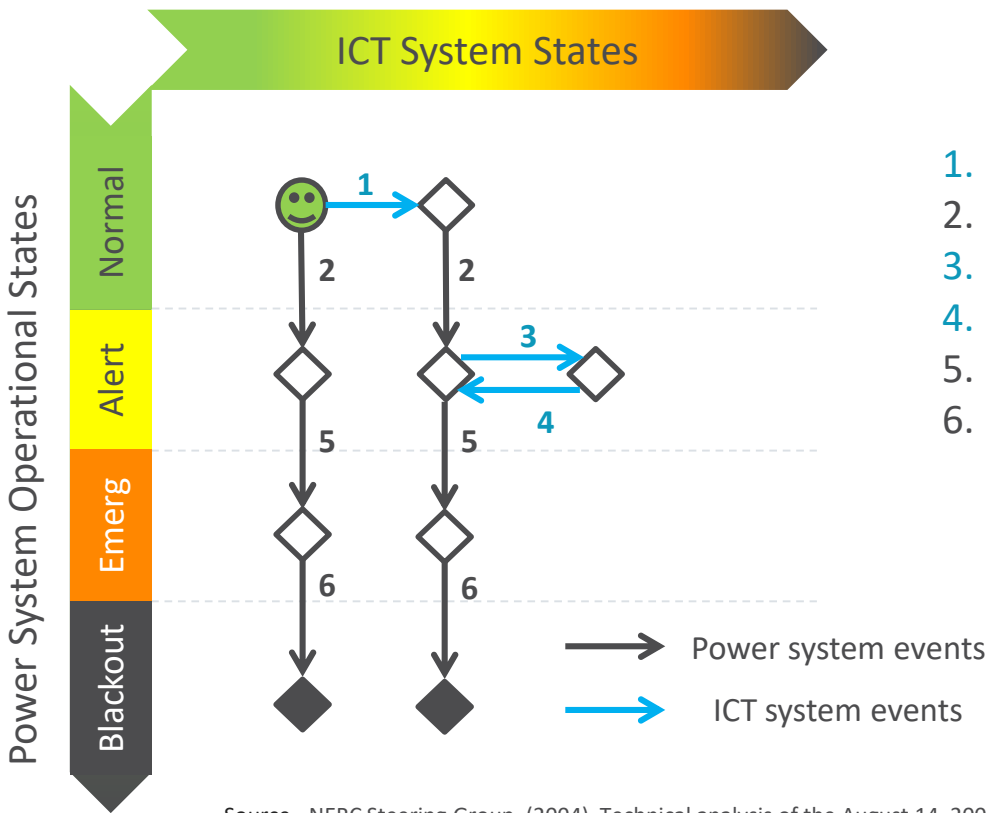
Strong interdependency brings-in new threats and vulnerabilities



Events are caused or aggravated by ICT events → Need to consider ICT in power system planning and operation

Motivation

Mapping of 2003 North American blackout



2003 North American blackout Events

1. State Estimator failure
2. Tripping of lines (DP&L)
3. Alarm system failure
4. State Estimator fixed with incorrect data
5. Tripping of lines (Chamberlin)
6. Voltage collapse

ICT status is missing!

Source - NERC Steering Group. (2004). Technical analysis of the August 14, 2003, blackout: What happened, why, and what did we learn. *Report to the NERC Board of Trustees*, 13.

Appropriate information, communication and automation systems are known from other domains

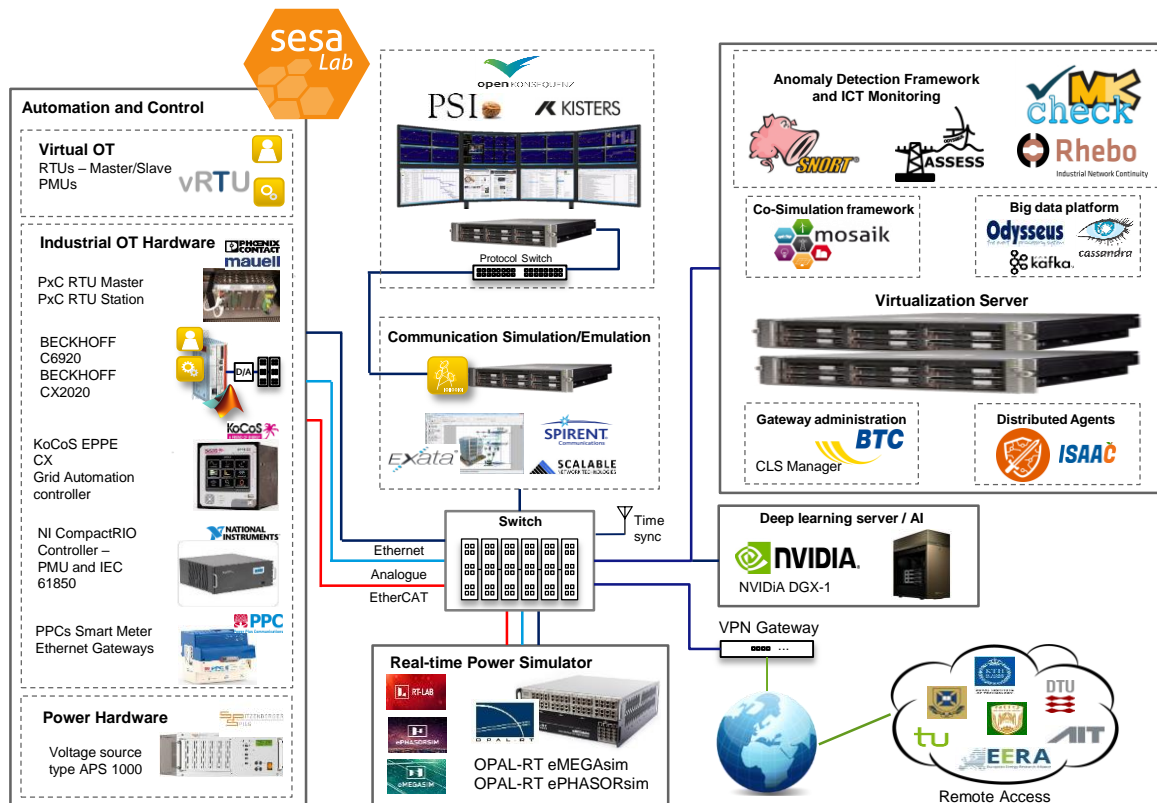
- > But: long-term use in safety critical energy systems mostly untested
- > Highly fraught with risk to stakeholders in the energy domain

Rigorous testing necessary!

- > Learning from other industrial domains...
- > „**Hardware in the Loop**“
- > Operation of a real el. controller hardware or a mechatronic component in a simulation of the real environment
- > *But: what belongs into this simulated environment?*
 - > How and on what parts of the system?
- > Remember: ...**holistic!**



Quelle: Daimler „Driving Simulator in Sindelfingen“, 2014





Examples of Testing Projects

ERIGrid vIED

Cross validation of virtual vs physical IEDs
Use-case: GOOSE messages quality test

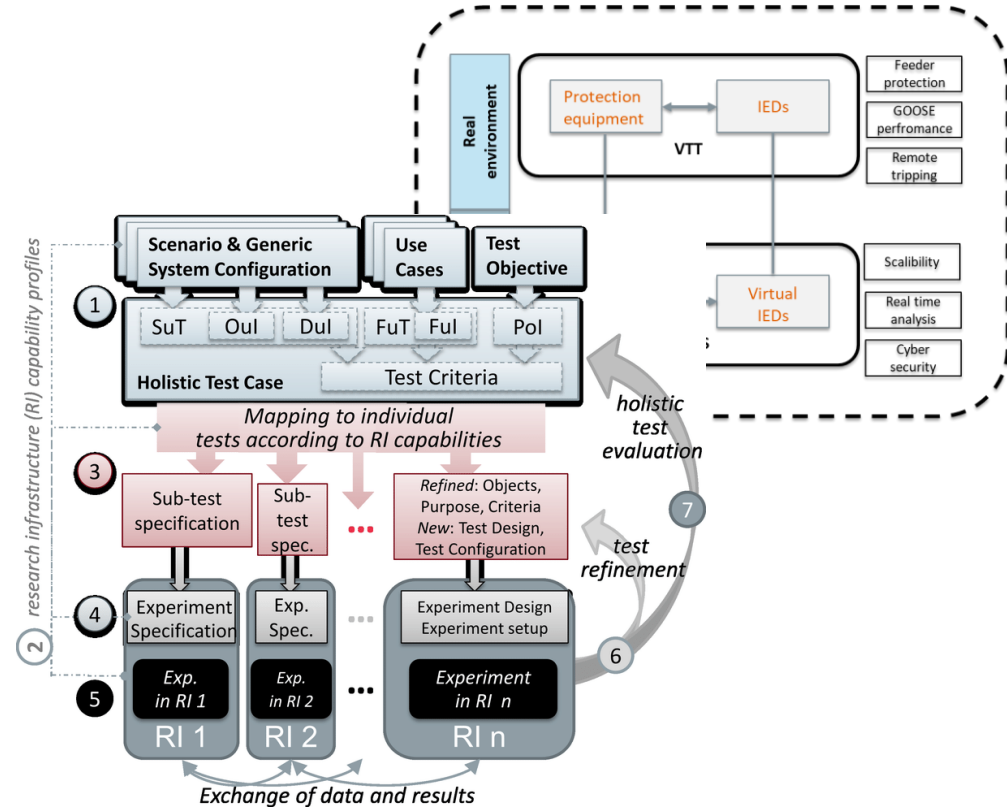
Enera

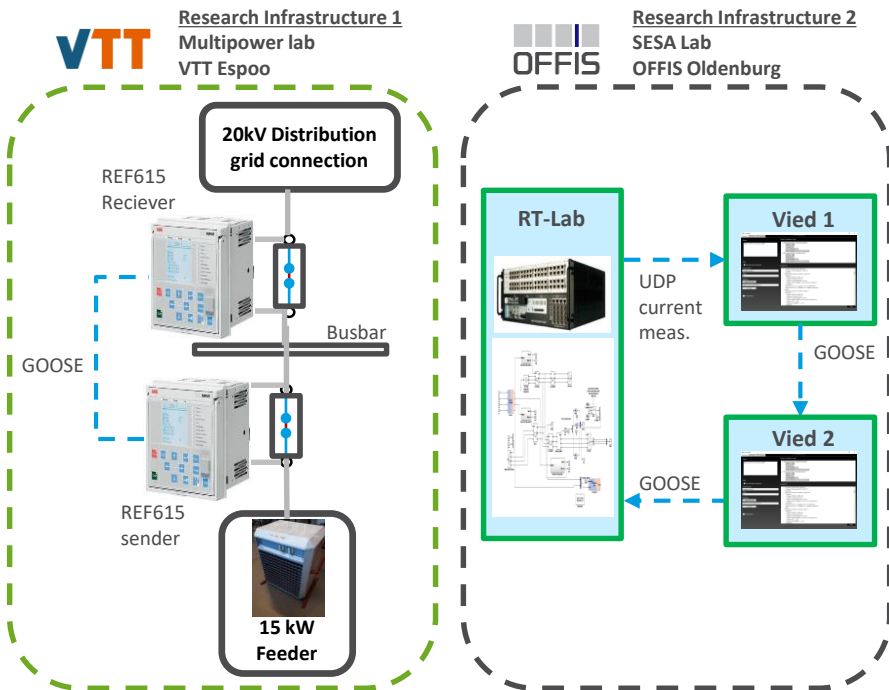
Testing performance of distributed controllers
Use-case: communication round trip testing

CybResLab

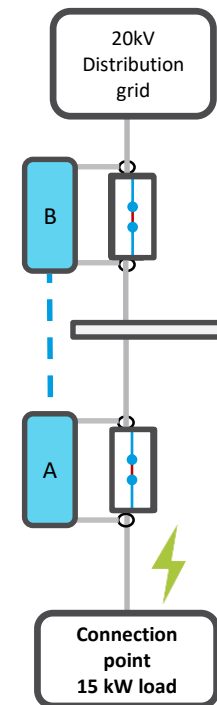
How to increase resilience of Smart Grid Services
Use-case: improved state estimation

- > Develop a virtual IEC61850 compliant virtual environment for large-scale simulation / virtualization studies
- > Validate the performance of virtual IED in a real-time set-up with the results from a physical set-up
 - > Test the performance of GOOSE and IEDs for reverse blocking scheme and validate it with physical set-up
 - > Define KPIs (GOOSE Transmission time, circuit breaker tripping time)
- > Use a **Holistic Testing Procedure** developed at ERIGrid for multi-domain multi-laboratory validation



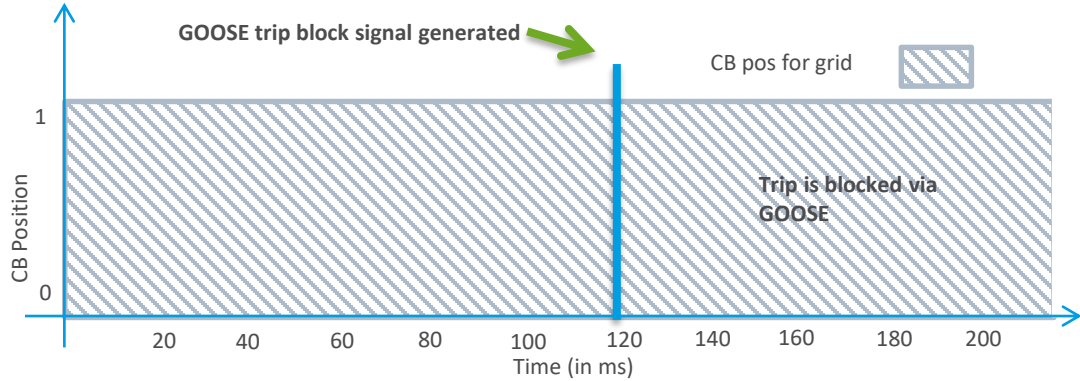


- > **Test case 1: Overcurrent at feeder load**
- > Relay A would trip and send blocking signals and circuit breaker status information to B
- > Message: Short circuit fault - do not trip IED B
 - > PTOC start
 - > XCBR status value
 - > 4ms average time
- > The messages are sent via GOOSE communication - Loss of mains protection
- > Fault is cleared and breaker is reclosed
- > **Test case 2: GOOSE communication failure**
 - > Blocking signal not sent



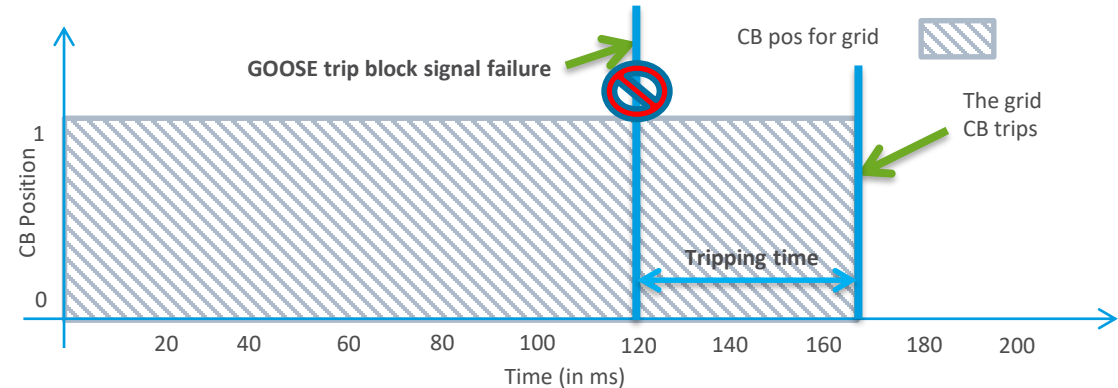
Test case 1

- > GOOSE message trip time
 - > RI 1 = 1.71ms
 - > RI 2 = still working on it



Test case 2

- > GOOSE communication is impaired
 - > Grid CB trips and grid connection point is lost



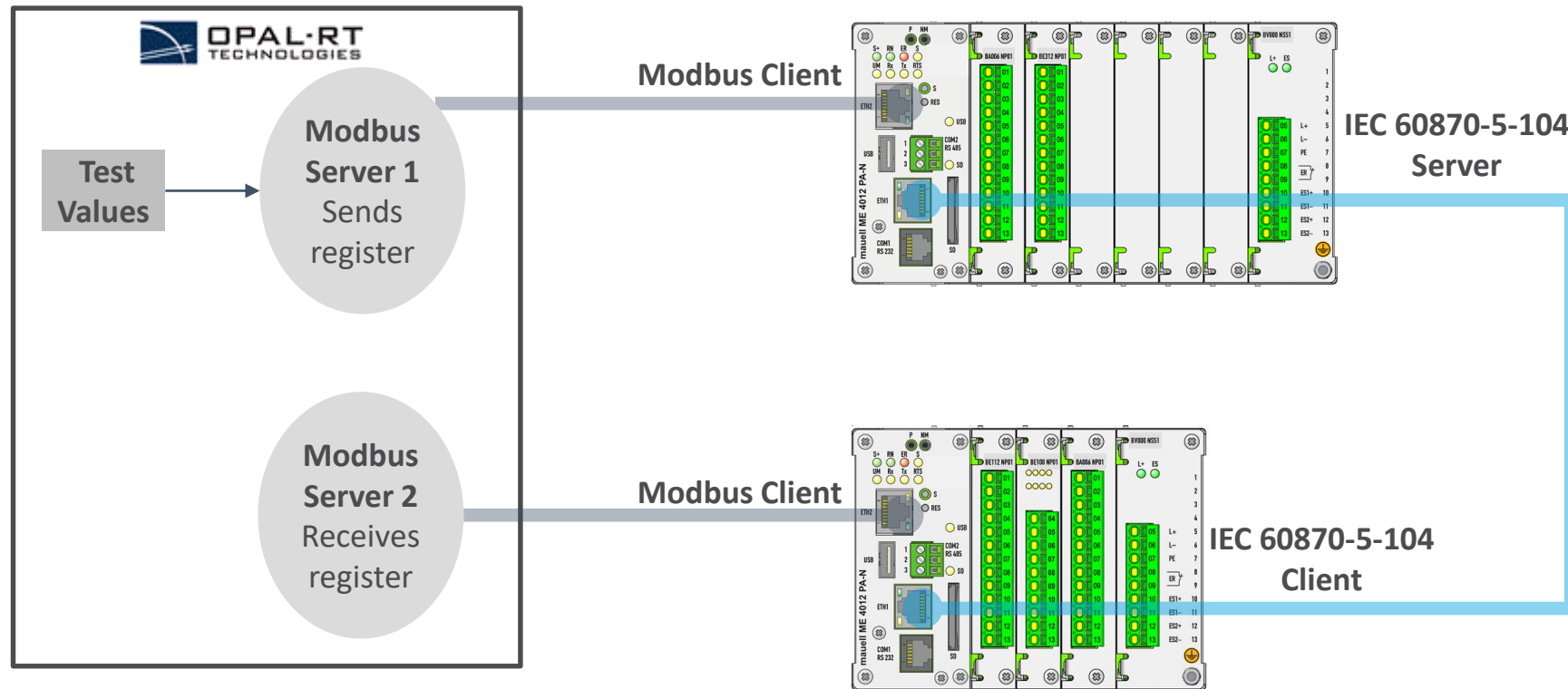


Distributed Controllers Testing

Hardware-in-loop Test

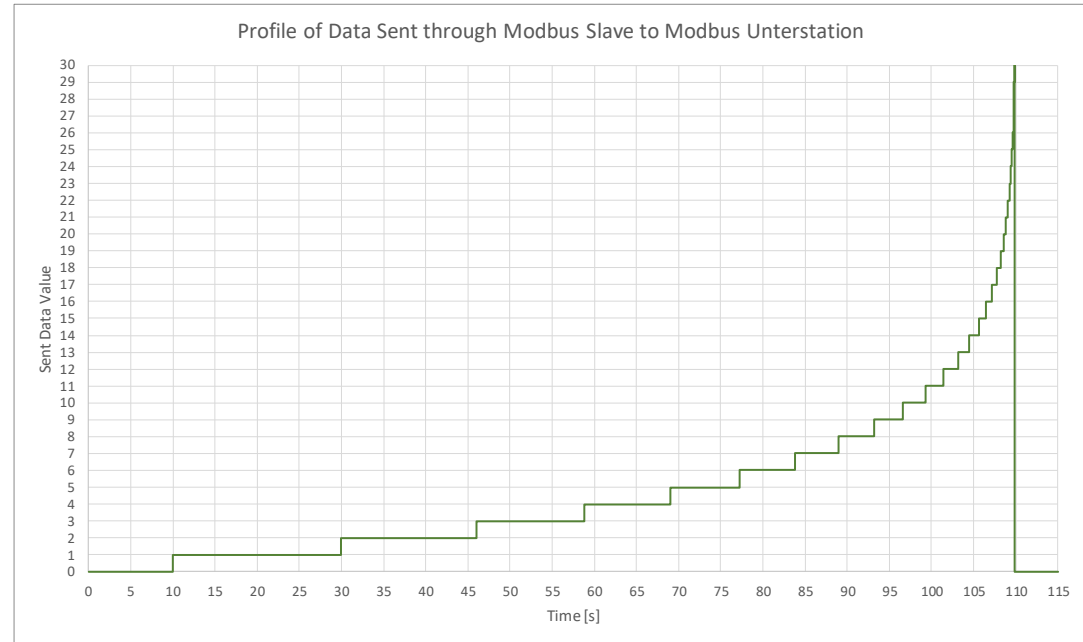
Determine capabilities and characteristics of Physical RTUs via HIL test.

Determine computational and communication delay

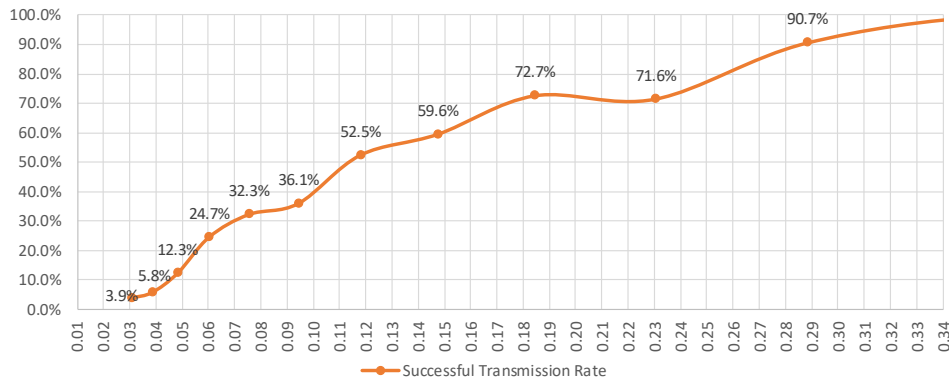


- > Data is sent with progressing change frequency rate
- > The successful data transmission is determined
- > The cut-off change frequency rate is determined
- > The experiment is performed **500 times** due to stochastic nature of communication.
- > The statistical delay is determined

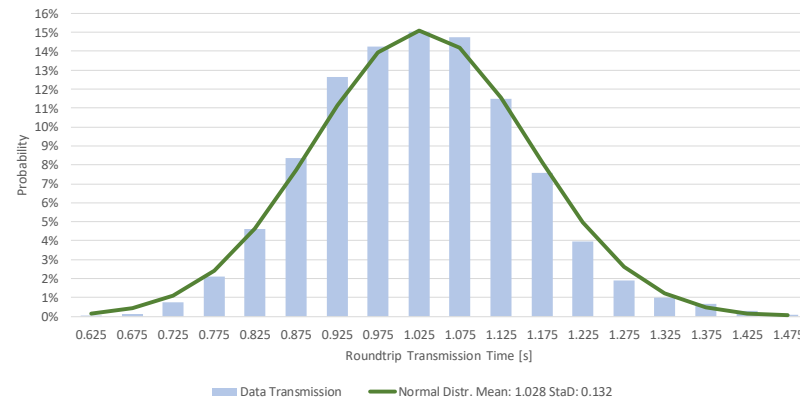
Value characteristic composed by integers



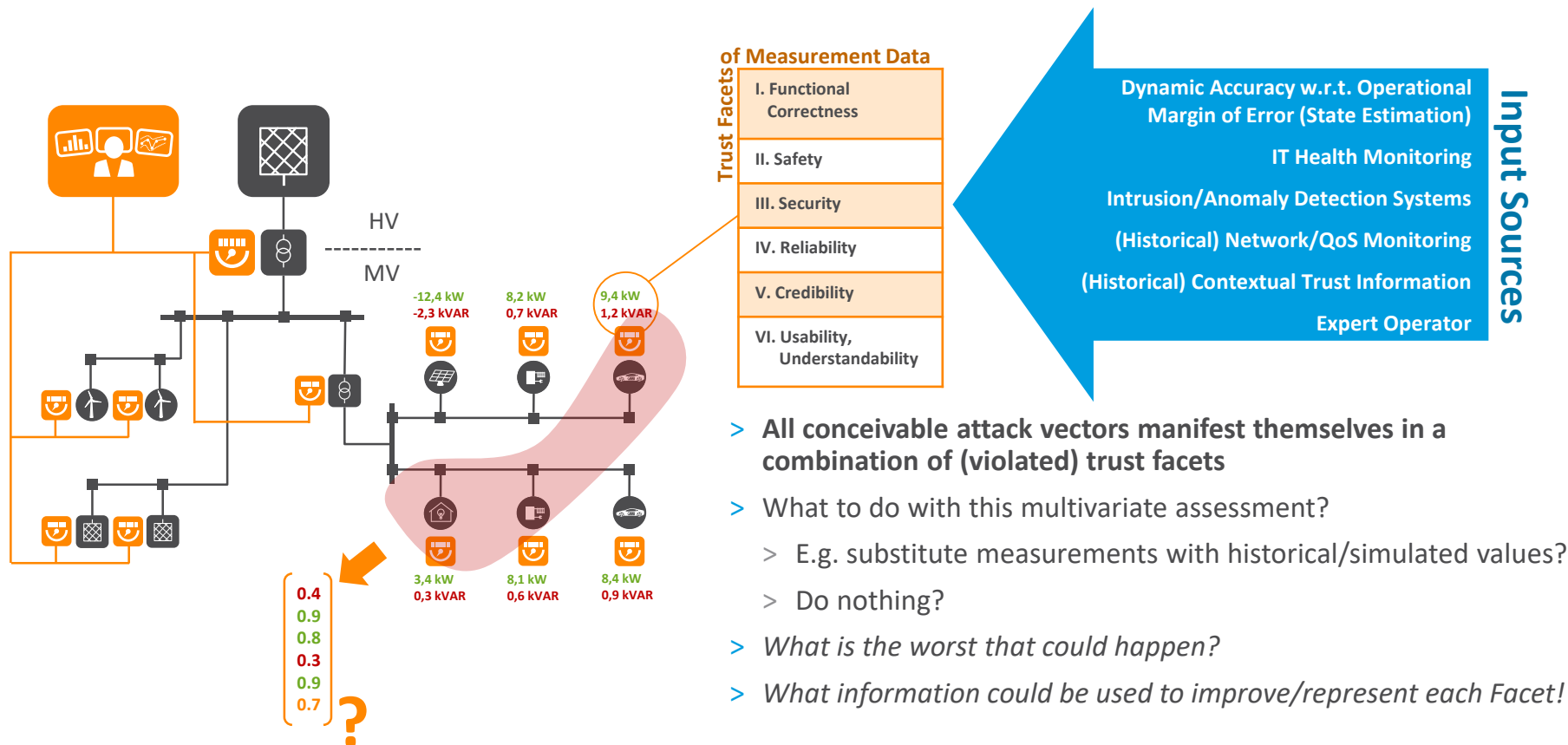
Successful Transmission Rate



Data Transmission Roundtrip Time Probability



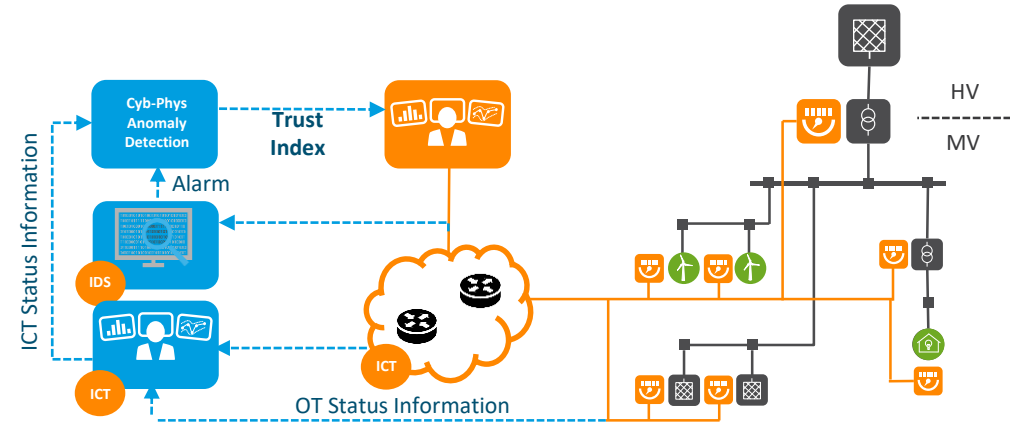
Average Real-Time Roundtrip: 1.028 s
Standard deviation: 0.132 s



Integration of OT/IT health status

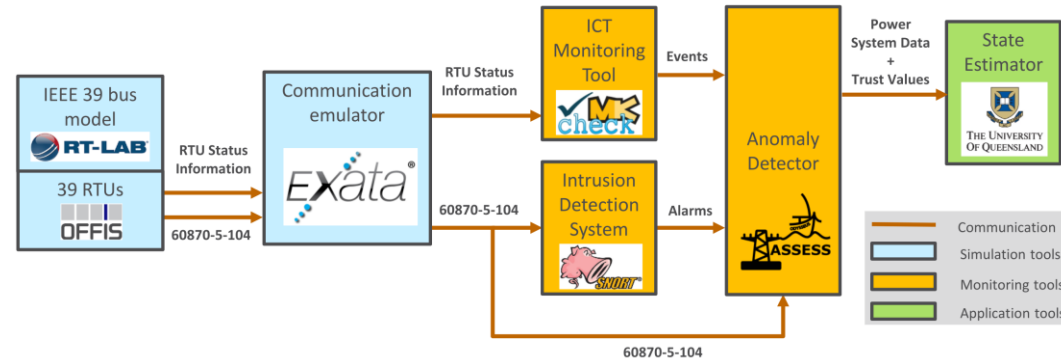
- ICT monitoring tools (e.g. interface and memory status,...)
- Intrusion Detection System (network malicious, ...)

Creating data reliability index (trustworthiness)

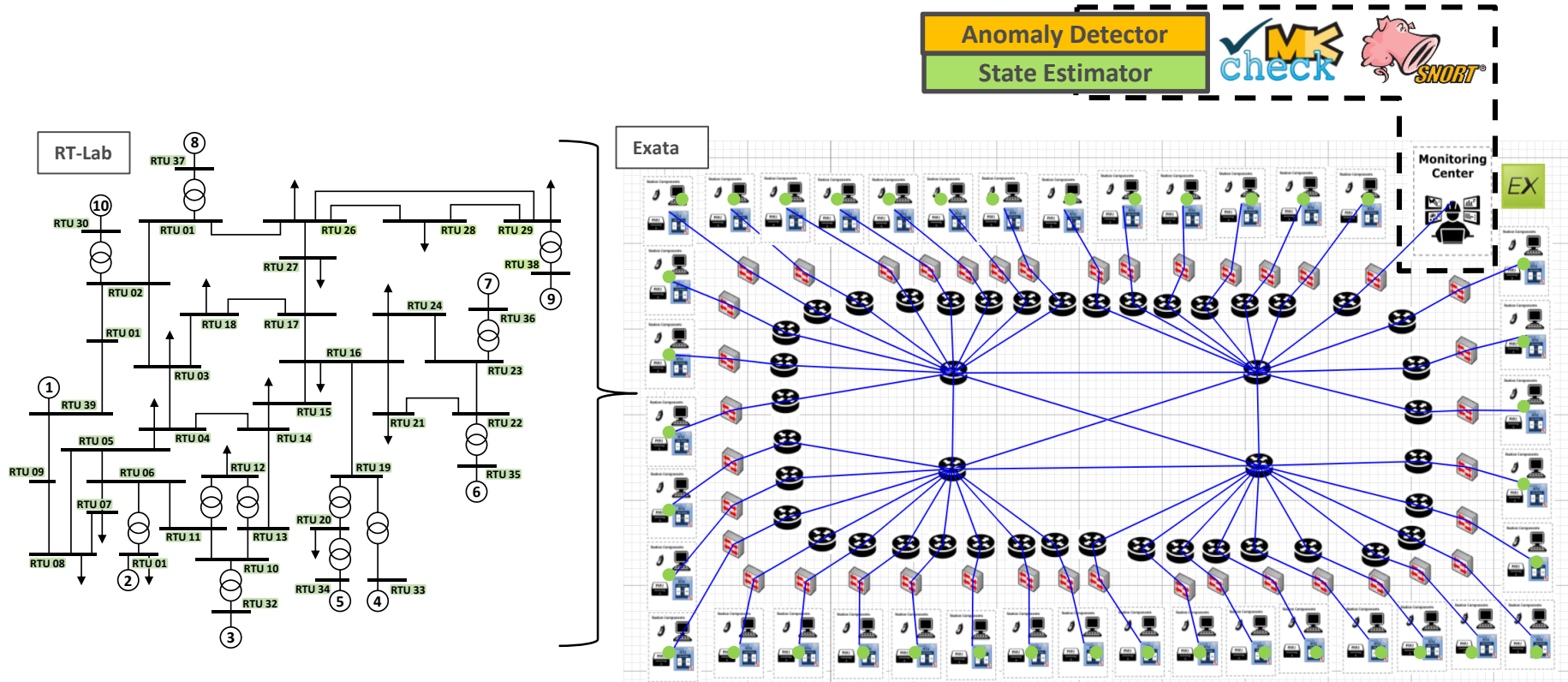


Application

- Improved (integrated) state estimation – identification and consideration of abnormal patterns
- ICT – Power systems state classification
- Selection of proper countermeasure
- Fault detection and management



Set-up in detailed

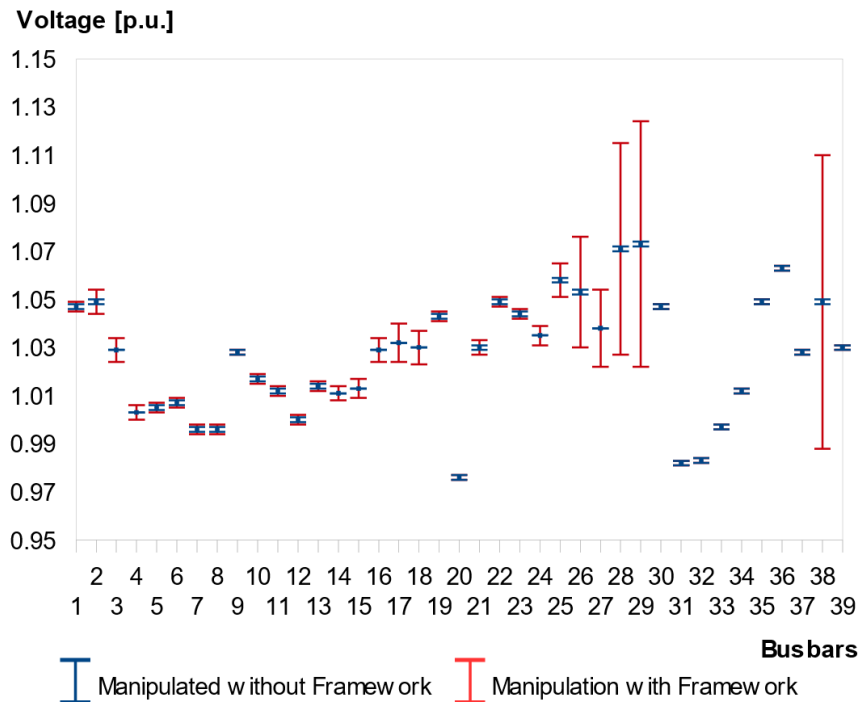


> Estimated state variables:

- > outside critical area: close to real values
- > inside critical area: different from real values

> Uncertainties (as a measure of trust)

- > without framework: almost zero everywhere
- > with framework: high inside critical area





Thank you!

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